

# Product data sheet

## Characteristics

# LXM32MC10N4

motion servo drive, Lexium 32, 100A, three phase, supply voltage 208 to 480V, 11kW



### Main

Range of product	Lexium 32
Device short name	LXM32M
Product or component type	Motion servo drive
Format of the drive	Book
Network number of phases	Three phase
[Us] rated supply voltage	380...480 V - 15...10 %
Supply voltage limits	323...528 V
Supply frequency	50/60 Hz - 5...5 %
Network frequency	47.5...63 Hz
EMC filter	Integrated
Continuous output current	40 A at 4 kHz
Output current 3s peak	100 A at 480 V for 5 s
Maximum continuous power	11000 W at 400 V 11000 W at 480 V
Nominal power	11 KW at 400 V 4 kHz 11 kW at 480 V 8 kHz
Line current	23.3 A 140 % at 480 V, without line choke 32 A 54 % at 480 V, with external line choke of 0.5 mH 38.1 A 70 % at 480 V, with external line choke of 0.5 mH

### Complementary

Switching frequency	4 kHz
Overvoltage category	III
Maximum leakage current	30 mA
Output voltage	<= power supply voltage
Electrical isolation	Between power and control
Type of cable	Single-strand IEC cable (temperature: 50 °C) copper 90 °C XLPE/EPR
Electrical connection	Terminal, clamping capacity: 8 mm <sup>2</sup> , AWG 8 (CN8)
Tightening torque	CN8: 3.8 N.m
Discrete input number	2 capture discrete input(s)
Discrete input type	Capture (CAP terminals)
Sampling duration	0.25 ms
Discrete input voltage	24 V DC for capture
Discrete input logic	Positive (compliment of STO_A, compliment of STO_B) at State 0: < 5 V at State 1: > 15 V conforming to EN/IEC 61131-2 type 1
Response time	<= 5 ms compliment of STO_A, compliment of STO_B
Discrete output number	3
Discrete output type	Logic output(s) (DO)24 V DC
Discrete output voltage	<= 30 V DC
Discrete output logic	Positive or negative (DO) conforming to EN/IEC 61131-2
Contact bounce time	<= 1 ms for compliment of STO_A, compliment of STO_B
Braking current	50 mA
Response time on output	250 µs (DO) for discrete output(s)

The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric Industries SAS nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.

Control signal type	Pulse train output (PTO) RS422 <500 kHz <100 m
Protection type	Against reverse polarity: inputs signal
Safety function	STO (safe torque off), integrated
Safety level	SIL 3 conforming to EN/IEC 61508
Communication interface	Modbus, integrated Profinet, with separated communication card
Connector type	RJ45 (labelled CN7) for Modbus
Commissioning port	2-wire RS485 multidrop for Modbus
Transmission rate	9600, 19200, 38400 bps for bus length of 40 m for Modbus
Number of addresses	1...247 for Modbus
Status LED	1 LED (red) servo drive voltage
Signalling function	Display of faults 7 segments
Marking	CE
Operating position	Vertical +/- 10 degree
Product compatibility	Servo motor BMH (190 mm, 1 motor stacks) Servo motor BMH (190 mm, 2 motor stacks) Servo motor BMH (190 mm, 3 motor stacks) Servo motor BMH (190 mm, 4 motor stacks)
Width	180 mm
Height	385 mm
Depth	240 mm
Net weight	9.6 kg

## Environment

Electromagnetic compatibility	Conducted EMC, class A group 1 conforming to EN 55011
Standards	EN/IEC 61800-3
Product certifications	CSA
IP degree of protection	IP20 conforming to EN/IEC 60529
Vibration resistance	1 gn (f= 13...150 Hz) conforming to EN/IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to EN/IEC 60028-2-27
Pollution degree	2 conforming to EN/IEC 61800-5-1
Environmental characteristic	Classes 3C1 conforming to IEC 60721-3-3
Relative humidity	Class 3K3 (5 to 85 %) without condensation conforming to IEC 60721-3-3
Ambient air temperature for operation	0...50 °C conforming to UL
Ambient air temperature for storage	-25...70 °C
Type of cooling	Integrated fan
Operating altitude	<= 1000 m without derating

## Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	34.5 cm
Package 1 Width	30.0 cm
Package 1 Length	56.0 cm
Package 1 Weight	10.348 kg
Unit Type of Package 2	P06
Number of Units in Package 2	2
Package 2 Height	80.0 cm
Package 2 Width	80.0 cm
Package 2 Length	60.0 cm
Package 2 Weight	35.0 kg

## Offer Sustainability

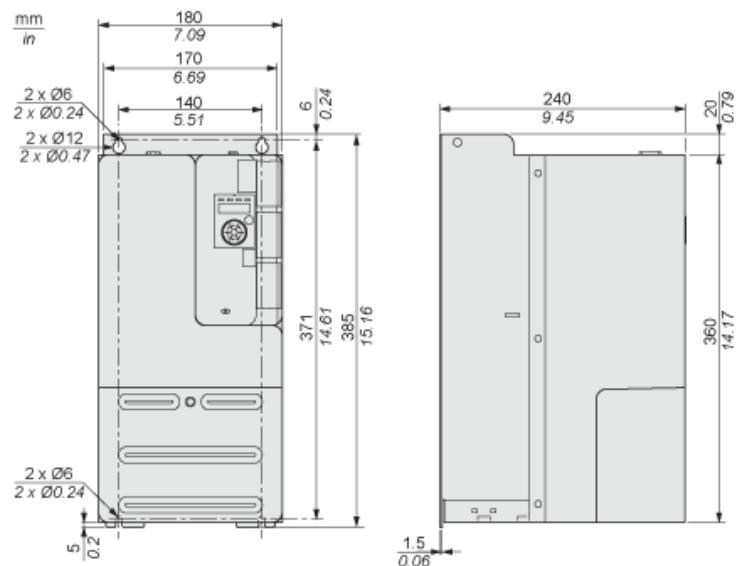
Sustainable offer status	Green Premium product
REACH Regulation	 <a href="#">REACH Declaration</a>
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope)
Mercury free	Yes
China RoHS Regulation	 <a href="#">China RoHS Declaration</a>
RoHS exemption information	 Yes
Environmental Disclosure	 <a href="#">Product Environmental Profile</a>
Circularity Profile	 <a href="#">End Of Life Information</a>
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
PVC free	Yes

## Contractual warranty

Warranty	18 months
----------	-----------

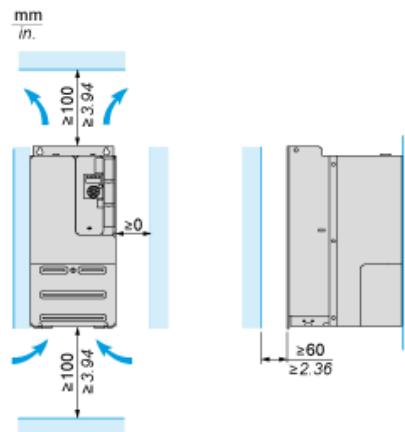
Lexium 32 Servo Drive

Dimensions



## Lexium 32 Motion Control Servo Drives

### Mounting Recommendations



LXM32MD85N4, LXM32MC10N4 servo drives have an integrated fan.

When selecting the position of the device in the control cabinet, note the following:

- Mount the device in a vertical position ( $\pm 10^\circ$ ). This is required for cooling the device.
- Adhere to the minimum installation distances for required cooling. Avoid heat accumulations.
- Do not mount the device close to heat sources.
- Do not mount the device on flammable materials.
- The heated airflow from other devices and components must not heat up the air used for cooling the device.
- If the thermal limits are exceeded during operation, the drive switches off (overtemperature).

NOTE: For cables that are connected via the underside of the servo drive, a free space  $\geq 200$  mm/7.87 in. is required under the unit to comply with the bending radius of the connection cables.

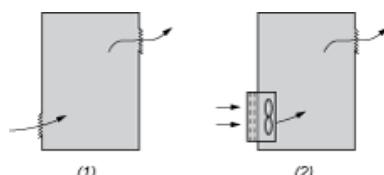
Ambient temperature	Mounting distances	Instructions to be followed
$0^\circ\text{C} \dots + 50^\circ\text{C}$	$d \geq 0$ mm	—

NOTE: Do not use insulated enclosures, as they have a poor level of conductivity.

### Recommendations for Mounting in an Enclosure

To ensure good air circulation in the servo drive:

- Fit ventilation grilles on the enclosure.
- Ensure that ventilation is adequate, otherwise install a forced ventilation unit with a filter.



(1) Natural convection  
(2) Forced ventilation

- Any apertures and/or fans must provide a flow rate at least equal to that of the servo drive fans (refer to characteristics).
- Use special filters with IP 54 protection.

### Mounting in Metal Enclosure (IP 54 Degree of Protection)

The servo drive must be mounted in a dust and damp proof enclosure in certain environmental conditions, such as dust, corrosive gases, high humidity with risk of condensation and dripping water, splashing liquid, etc. In these cases, Lexium 32 servo drives can be installed in an enclosure where the internal temperature must not exceed  $60^\circ\text{C}$ .